On Lorentzian α -Sasakian Manifolds

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ABSTRACT. The present paper deals with Lorentzian α -Sasakian manifolds with conformally flat and quasi conformally flat curvature tensor. It is shown that in both cases, the manifold is locally isometric with a sphere $S^{2^n+1}(c)$. Further it is shown that an Lorentzian α -Sasakian manifold with R(X,Y).C=0 is locally isometric with a sphere $S^{2^n+1}(c)$, where $c=\alpha^2$.

0. Introduction

In [9], S. Tanno classified connected almost contact metric manifolds whose automorphism groups possess the maximum dimension. For such a manifold, the sectional curvature of plane sections containing ξ is a constant, say c. He showed that they can be divided into three classes:

- (1) homogeneous normal contact Riemannian manifolds with c > 0,
- (2) global Riemannian products of a line or a circle with a Kaehler manifold of constant holomorphic sectional curvature if c = 0 and
- (3) a warped product space $\mathbb{R} \times_f \mathbb{C}$ if c < 0.

It is known that the manifolds of class (1) are characterized by admitting a Sasakian structure. Kenmotsu ([18]) characterized the differential geometric properties of the manifolds of class (3); the structure so obtained is now known as Kenmotsu structure. In general, these structures are not Sasakian ([18]).

In the Gray-Hervella classification of almost Hermitian manifolds ([13]), there appears a class, W_4 , of Hermitian manifolds which are closely related to locally

Received January 7, 2004.

²⁰⁰⁰ Mathematics Subject Classification: 53D10, 53C25, 53C15.

Key words and phrases: trans-Sasakian manifolds, α -Sasakian manifolds, Lorentzian α -Sasakian manifolds.

conformal Kaehler manifolds ([20]). An almost contact metric structure on a manifold M is called a trans-Sasakian structure ([11]) if the product manifold $M \times \mathbb{R}$ belongs to the class W_4 . The class $C_6 \oplus C_5$ ([16], [18]) coincides with the class of the trans-Sasakian structures of type (α, β) . In fact, in [18], local nature of the two subclasses, namely, C_5 and C_6 structures, of trans-Sasakian structures are characterized completely.

We note that trans-Sasakian structures of type (0,0), $(0,\beta)$ and $(\alpha,0)$ are cosymplectic ([1]), β -Kenmotsu ([19]) and α -Sasakian ([19]) respectively. In ([12]) it is proved that trans-Sasakian structures are generalized quasi-Sasakian ([17]). Thus, trans-Sasakian structures also provide a large class of generalized quasi-Sasakian structures.

An almost contact metric structure (ϕ, ξ, η, g) on M is called a trans-Sasakian structure ([11]) if $(M \times \mathbb{R}, J, G)$ belongs to the class $W_4([13])$, where J is the almost complex structure on $M \times \mathbb{R}$ defined by

$$J(X, fd/dt) = (\phi X - f\xi, \eta(X) fd/dt)$$

for all vector fields X on M and smooth functions f on $M \times \mathbb{R}$, and G is the product metric on $M \times \mathbb{R}$. This may be expressed by the condition ([21])

$$(\nabla_X \phi)Y = \alpha(g(X, Y)\xi - \eta(Y)X) + \beta(g(\phi X, Y)\xi - \eta(Y)\phi X)$$

for some smooth functions α and β on M, and we say that the trans-Sasakian structure is of type (α, β) .

Let (x, y, z) be Cartesian coordinates in \mathbb{R}^3 , then (ϕ, ξ, η, q) given by

$$\xi = \partial/\partial z, \quad \eta = dz - ydx, \quad \phi = \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & -y & 0 \end{pmatrix}, \quad g = \begin{pmatrix} e^z + y^2 & 0 & -y \\ 0 & e^z & 0 \\ -y & 0 & 1 \end{pmatrix}$$

is a trans-Sasakian structure of type $(-1/(2e^z), 1/2)$ in $\mathbb{R}^3([21])$. In general, in a 3-dimensional K-contact manifold with structures tensors (ϕ, ξ, η, g) for a non-constant function f, if we define $g' = fg + (1 - f)\eta \otimes \eta$; then (ϕ, ξ, η, g') is a trans-Sasakian structure of type $(1/f, (1/2)\xi(\ln f))([14], [15], [16])$.

Corollary 1 ([7]). A trans-Sasakian structure of type (α, β) with α a nonzero constant is always α -Sasakian.

In this case α becomes a constant. If $\alpha=1,$ then $\alpha\text{-Sasakian}$ manifold is Sasakian.

In this paper, we investigate Lorentzian α -Sasakian manifolds in which

$$(1) C = 0$$

where C is the Weyl conformal curvature tensor. Then we study Lorentzian α -Sasakian manifolds in which

$$(2) \qquad \qquad \widetilde{C} = 0$$

where C is the quasi conformal curvature tensor. In the both cases, it is shown that an Lorentzian α -Sasakian manifold is isometric with a sphere $S^{2n+1}(c)$, where $c = \alpha^2$. Finally, an Lorentzian α -Sasakian manifold with

$$(3) R(X,Y).C = 0$$

has been considered, where R(X,Y) is considered as a derivation of the tensor algebra at each point of the manifold of tangent vectors X,Y. It is easy to see that R(X,Y).R=0 implies R(X,Y).C=0. So it is meaningful to undertake the study of manifolds satisfying the condition (3).

1. Preliminaries

A differentiable manifold of dimension (2n+1) is called Lorentzian α -Sasakian manifold if it admits a (1,1)-tensor field ϕ , a contravariant vector field ξ , a covariant vector field η and Lorentzian metric g which satisfy ([2], [3], [4], [5], [6], [7])

$$\eta(\xi) = -1,$$

$$\phi^2 = I + \eta \otimes \xi,$$

(6)
$$g(\phi X, \phi Y) = g(X, Y) + \eta(X)\eta(Y),$$

$$g(X,\xi) = \eta(X),$$

(8)
$$\phi \xi = 0, \qquad \eta(\phi X) = 0$$

for all $X, Y \in TM$.

Also an Lorentzian α -Sasakian manifold M is satisfying ([8])

(9)
$$\nabla_X \xi = -\alpha \phi X,$$

$$(10) \qquad (\nabla_X \eta) Y = -\alpha q(\phi X, Y).$$

where ∇ denotes the operator of covariant differentiation with respect to the Lorentzian metric g.

An Lorentzian α -Sasakian manifold M is said to be η -Einstein if its Ricci tensor S is of the form

(11)
$$S(X,Y) = ag(X,Y) + b\eta(X)\eta(Y)$$

for any vector fields X, Y, where a, b are functions on M.

Further, on an Lorentzian α -Sasakian manifold M the following relations hold ([7], [10])

(12)
$$R(\xi, X)Y = \alpha^2(g(X, Y)\xi - \eta(Y)X),$$

(13)
$$R(X,Y)\xi = \alpha^2(\eta(Y)X - \eta(X)Y),$$

(14)
$$R(\xi, X)\xi = \alpha^2(\eta(X)\xi + X),$$

$$(15) S(X,\xi) = 2n\alpha^2 \eta(X),$$

$$(16) Q\xi = 2n\alpha^2 \xi,$$

$$(17) S(\xi, \xi) = -2n\alpha^2,$$

where S is the Ricci curvature and Q is the Ricci operator given by S(X,Y) = g(QX,Y).

2. Lorentzian α -Sasakian manifolds with C=0

The conformal curvature tensor C on M^{2n+1} is defined as

(18)
$$C(X,Y)Z = R(X,Y)Z + \frac{1}{2n-1} \begin{bmatrix} S(X,Z)Y - S(Y,Z)X \\ +g(X,Z)QY - g(Y,Z)QX \end{bmatrix} - \frac{\tau}{2n(2n-1)} [g(X,Z)Y - g(Y,Z)X]$$

where

$$S(X,Y) = q(QX,Y).$$

Using (1) we get from (18)

(19)
$$R(X,Y)Z = \frac{1}{2n-1} \begin{bmatrix} S(Y,Z)X - S(X,Z)Y \\ +g(Y,Z)QX - g(X,Z)QY \end{bmatrix} + \frac{\tau}{2n(2n-1)} [g(X,Z)Y - g(Y,Z)X].$$

Taking $Z = \xi$ in (19) and using (7), (13) and (15), we find

$$(\alpha^{2} + \frac{\tau}{2n(2n-1)} - \frac{2n\alpha^{2}}{(2n-1)})(\eta(Y)X - \eta(X)Y)$$

$$= \frac{1}{2n-1}(\eta(Y)QX - \eta(X)QY).$$

Taking $Y = \xi$ and using (4) we get

(20)
$$QX = \left(\frac{\tau}{2n} - \alpha^2\right)X + \left(\frac{\tau}{2n} - \alpha^2 - 2n\alpha^2\right)\eta(X)\xi.$$

Thus the manifold is η -Einstein.

Contracting (20) we get

$$\tau = 2n(2n+1)\alpha^2.$$

Using (21) in (20) we find

$$(22) QX = 2n\alpha^2 X.$$

Putting (22) in (19) we get after a few steps

(23)
$$R(X,Y)Z = \alpha^2(g(Y,Z)X - g(X,Z)Y).$$

Thus a conformally flat Lorentzian α -Sasakian manifold is of constant curvature. The value of this constant is α^2 . Hence we can state.

Theorem 2. A conformally flat Lorentzian α -Sasakian manifold is locally isometric to a sphere $S^{2n+1}(c)$, where $c = \alpha^2$.

3. Lorentzian α -Sasakian manifolds with $\tilde{C}=0$

The quasi conformal curvature tensor \tilde{C} on M^{2n+1} is defined as

(24)
$$\widetilde{C}(X,Y)Z = aR(X,Y)Z + b\{S(Y,Z)X - S(X,Z)Y + g(Y,Z)QX - g(X,Z)QY\}$$
$$- \frac{\tau}{(2n+1)}(\frac{a}{2n} + 2b)\{g(Y,Z)X - g(X,Z)Y\}$$

where a, b are constants such that $ab \neq 0$ and

$$S(Y,Z) = g(QY,Z).$$

Using (2), we find from (24)

(25)
$$R(X,Y)Z = -\frac{b}{a} \{ S(Y,Z)X - S(X,Z)Y + g(Y,Z)QX - g(X,Z)QY \}$$

 $+ \{ \frac{\tau}{(2n+1)a} (\frac{a}{2n} + 2b) \} \{ g(Y,Z)X - g(X,Z)Y \}.$

Taking $Z = \xi$ in (25) and using (7), (13) and (15), we get

(26)
$$\alpha^{2}(\eta(Y)X - \eta(X)Y) = -\frac{b}{a} \{\eta(Y)QX - \eta(X)QY\} + \{\frac{\tau}{(2n+1)a}(\frac{a}{2n} + 2b) - \frac{2n\alpha^{2}b}{a}\}(\eta(Y)X - \eta(X)Y).$$

Taking $Y = \xi$ and applying (4) we have

(27)
$$QX = \left\{ \frac{\tau}{(2n+1)b} \left(\frac{a}{2n} + 2b \right) - 2n\alpha^2 - \frac{a}{b}\alpha^2 \right\} X + \left\{ \frac{\tau}{(2n+1)b} \left(\frac{a}{2n} + 2b \right) - 4n\alpha^2 - \frac{a}{b}\alpha^2 \right\} \eta(X) \xi.$$

Contracting (27), we get after a few steps

$$\tau = 2n(2n+1)\alpha^2.$$

Using (28) in (27), we get

$$(29) QX = 2n\alpha^2 X.$$

Finally, using (29), we find from (25)

$$R(X,Y)Z = \alpha^2 \{ g(Y,Z)X - g(X,Z)Y \}.$$

Thus we can state

Theorem 3. A quasi conformally flat Lorentzian α -Sasakian manifold is locally isometric to a sphere $S^{2n+1}(c)$, where $c = \alpha^2$.

4. Lorentzian α -Sasakian manifolds satisfying R(X,Y).C=0

Using (7), (12) and (15) we take $X = \xi$, we find from (18)

(30)
$$\eta(C(X,Y)Z) = \frac{1}{2n-1} [(\frac{\tau}{2n} - \alpha^2) \{ g(Y,Z) \eta(X) - g(X,Z) \eta(Y) \} - \{ S(Y,Z) \eta(X) - S(X,Z) \eta(Y) \}].$$

Putting $Z = \xi$ in (30) and using (7) and (15), we get

(31)
$$\eta(C(X,Y)\xi) = 0.$$

Again $X = \xi$ in (30)

(32)
$$\eta(C(\xi, Y)Z) = (\alpha^2 - \frac{2n\alpha^2}{2n-1} + \frac{\tau}{2n(2n+1)})g(Y, Z) - (\alpha^2 - \frac{4n\alpha^2}{2n-1} + \frac{\tau}{2n(2n+1)})\eta(Y)\eta(Z) - \frac{1}{2n-1}S(Y, Z).$$

Now

(33)
$$(R(\xi, Y)C)(U, V)W = R(\xi, Y)C(U, V)W - C(R(\xi, Y)U, V)W - C(U, R(\xi, Y)V)W - C(U, V)R(\xi, Y)W.$$

Using (3), we find from above

$$g[R(\xi, Y)C(U, V)W, \xi] - g[C(R(\xi, Y)U, V)W, \xi] - g[C(R(\xi, Y)UV)W, \xi] - g[C(U, V)R(\xi, Y)W, \xi] = 0.$$

Using (7) and (12) we get

(34)
$$-\alpha^{2}g(C(U,V)W,Y) - \alpha^{2}\eta(Y)\eta(C(U,V)W) - \alpha^{2}g(Y,U)\eta(C(\xi,V)W)$$

$$+\alpha^{2}\eta(U)\eta(C(Y,V)W) - \alpha^{2}g(Y,V)\eta(C(U,\xi)W) + \alpha^{2}\eta(V)\eta(C(U,Y)W)$$

$$-\alpha^{2}g(Y,W)\eta(C(U,V)\xi) + \alpha^{2}\eta(W)\eta(C(U,V)Y) = 0.$$

Putting U = Y in (34)

(35)
$$-\alpha^{2}g(C(U,V)W,U) - \alpha^{2}\eta(U)\eta(C(U,V)W) - \alpha^{2}g(U,U)\eta(C(\xi,V)W) + \alpha^{2}\eta(U)\eta(C(U,V)W) - \alpha^{2}g(U,V)\eta(C(U,\xi)W) + \alpha^{2}\eta(V)\eta(C(U,U)W) - \alpha^{2}g(U,W)\eta(C(U,V)\xi) + \alpha^{2}\eta(W)\eta(C(U,V)U) = 0.$$

Let $\{\widetilde{e_i}: i=1,\cdots,2n+1\}$ be an orthonormal basis of the tangent space at any point, then the sum for $1\leq i\leq n$ of the relations (35) for $U=\widetilde{e_i}$ gives

$$-2n\alpha^2 \eta(C(\xi, V)W) = 0,$$

$$\eta(C(\xi, V)W) = 0 \text{ as } n > 1.$$

Using (31) and (36), (34) takes the form

(37)
$$-\alpha^2 g(C(U,V)W,Y) - \alpha^2 \eta(Y) \eta(C(U,V)W) + \alpha^2 \eta(U) \eta(C(Y,V)W) + \alpha^2 \eta(V) \eta(C(U,Y)W) + \alpha^2 \eta(W) \eta(C(U,V)Y)$$
$$= 0.$$

Using (30) in (37), we get

$$(38) \qquad -\alpha^{2}g(C(U,V)W,Y) \\ +\alpha^{2}\eta(W)\frac{1}{2n-1}[(\frac{\tau}{2n}-1)\{\eta(U)g(Y,V)-\eta(V)g(U,Y)\} \\ -\{\eta(U)S(Y,V)-\eta(V)S(U,Y)\}] \\ = 0.$$

In virtue of (36), (32) reduces to

(39)
$$S(Y,Z) = (\frac{\tau}{2n} - \alpha^2)g(Y,Z) + (\frac{\tau}{2n+1} - (2n+1)\alpha^2)\eta(Y)\eta(Z).$$

Using (39), (37) reduces to

$$(40) -\alpha^2 q(C(U,V)W,Y) = 0,$$

i.e.,

$$(41) C(U,V)W = 0.$$

Hence the manifold is conformally flat. Using the Theorem 1, we state

Theorem 4. If in an Lorentzian α -Sasakian manifold $M^{2n+1}(n \ge 1)$ the relation R(X,Y).C = 0 holds, then it is locally isometric with a sphere $S^{2n+1}(c)$, where $c = \alpha^2$.

For a conformally symmetric Riemannian manifold [1], we have $\nabla C = 0$. Hence for such a manifold R(X,Y).C = 0 holds. Thus we have the following corollary of the above theorem:

Corollary 5. A conformally symmetric Lorentzian α -Sasakian manifold M^{2n+1} $(n \ge 1)$ is locally isometric with a sphere $S^{2n+1}(c)$, where $c = \alpha^2$.

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